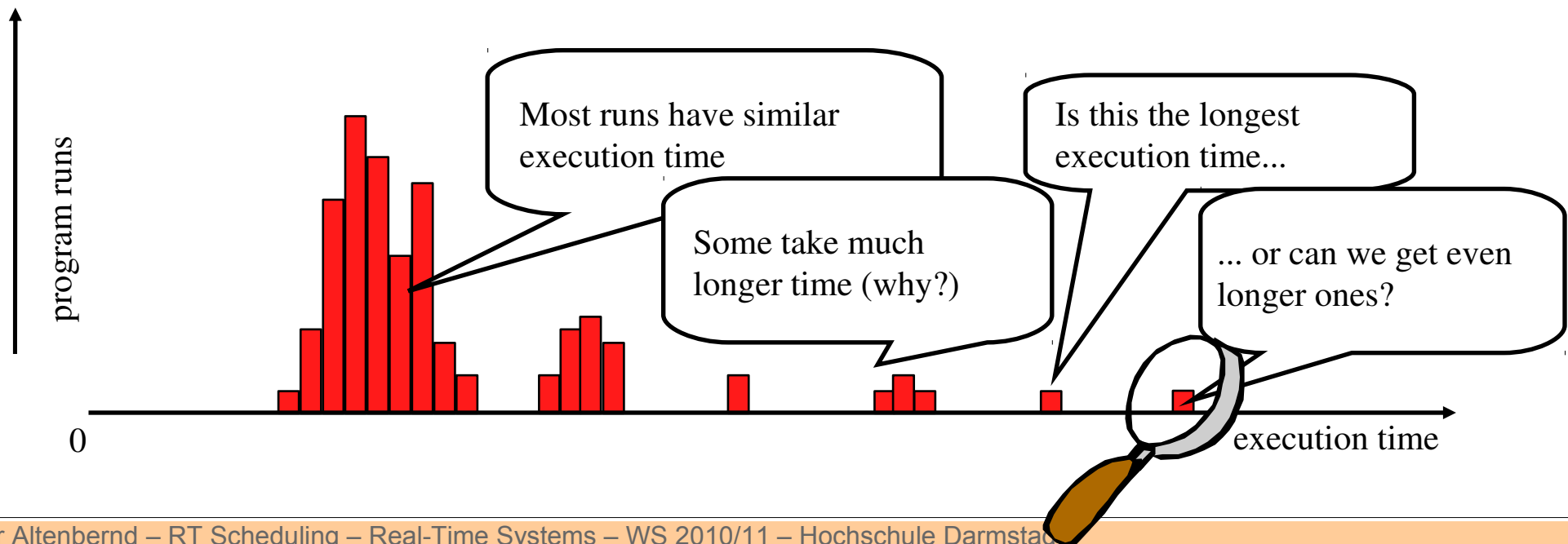

Vorlesung Real-Time Systems

2. Exkurs: WCET Analyse

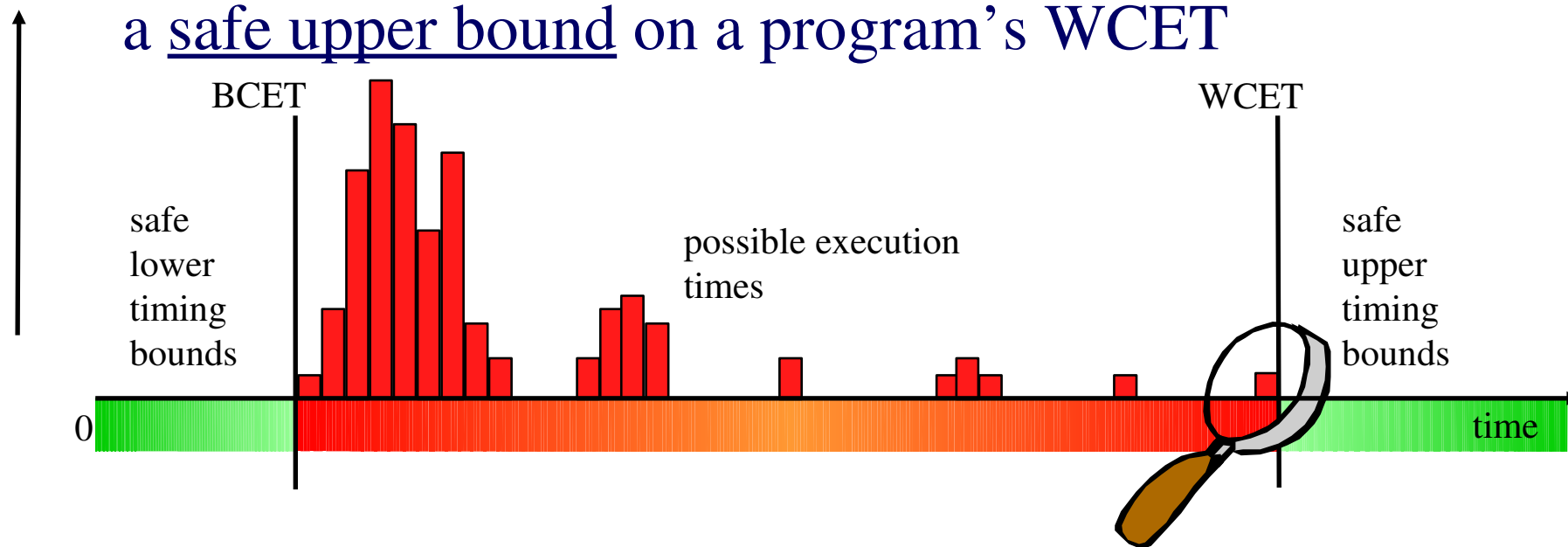
Program timing basics

- Most computer programs have varying execution time
 - Due to input values
 - Due to software characteristics
 - Due to hardware characteristics
- Example: some timed program runs



WCET and WCET analysis

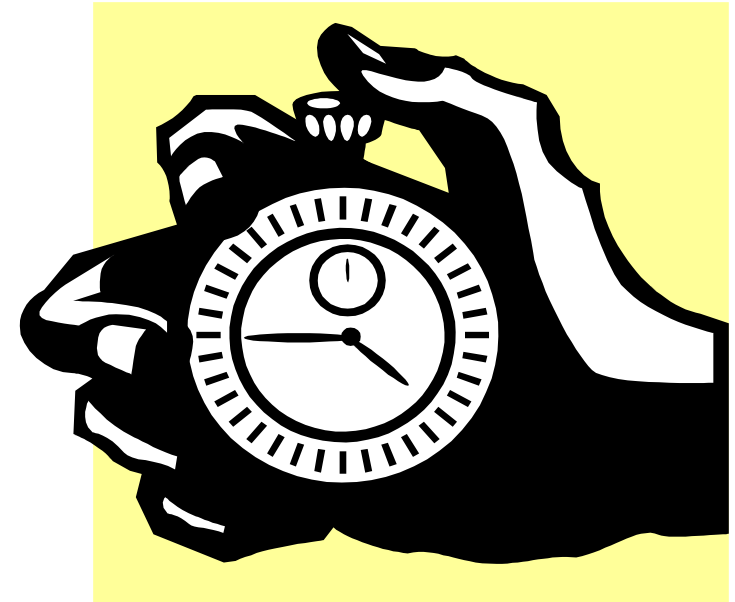
- Worst-Case Execution Time = WCET
 - The longest calculation time possible
 - For one program/task when run in isolation
 - Other interesting measures: BCET, ACET
- The goal of a WCET analysis is to derive a safe upper bound on a program's WCET



Measuring for the WCET

- Methodology:

- Determine potential "worst-case input"
- Run and measure
- Add a safety margin



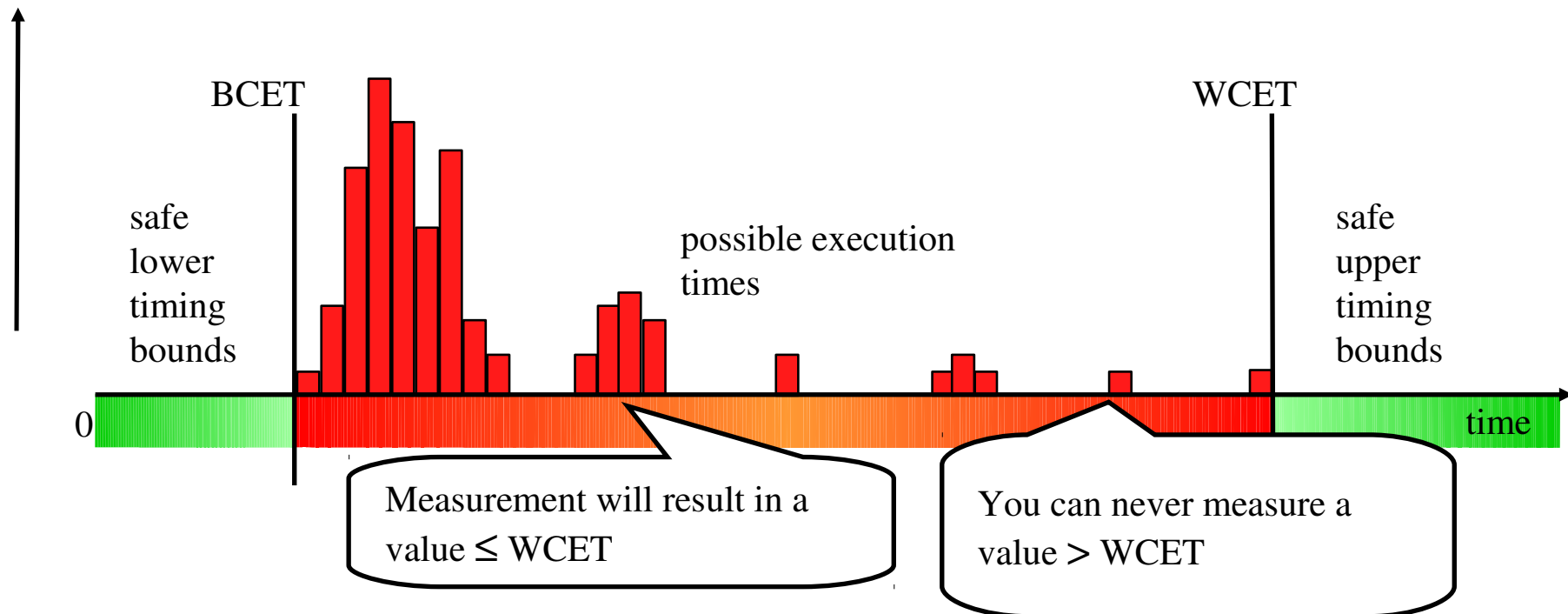
Measurement issues

- **Large number of potential worst-case inputs**
 - Program state might be part of input
- **Has the worst-case path really been taken?**
 - Often many possible paths through a program
 - Hardware features may interact in unexpected ways
- **How to monitor the execution?**
 - The instrumentation may affect the timing
 - How much instrumentation output can be handled?



Problem of using measurement

- Measured value never larger than WCET!

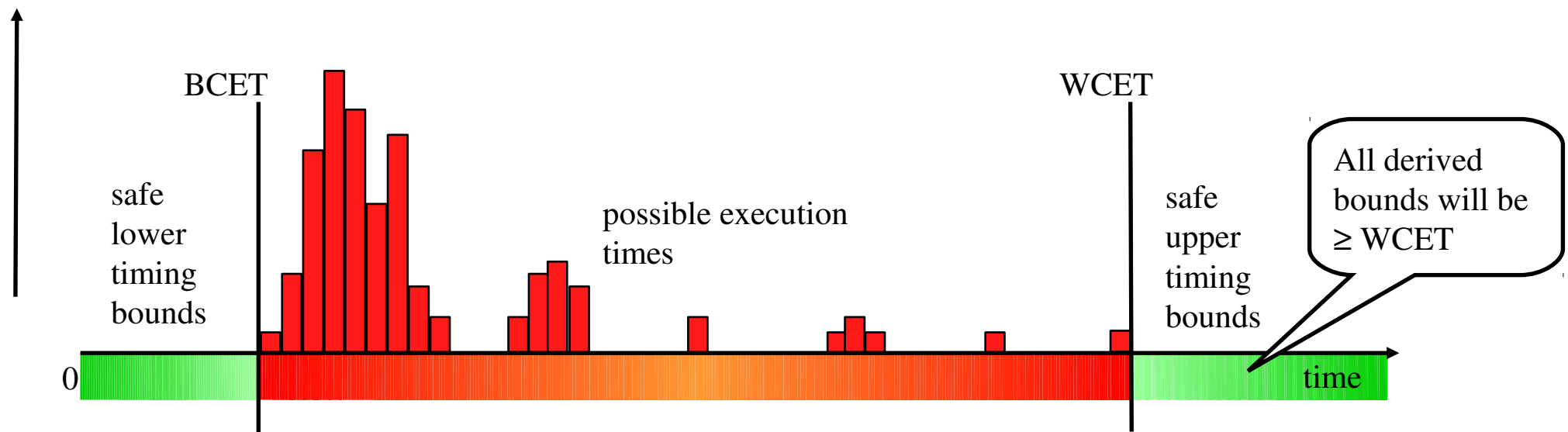


A safety margin must be added!

How much is enough?

Static WCET analysis

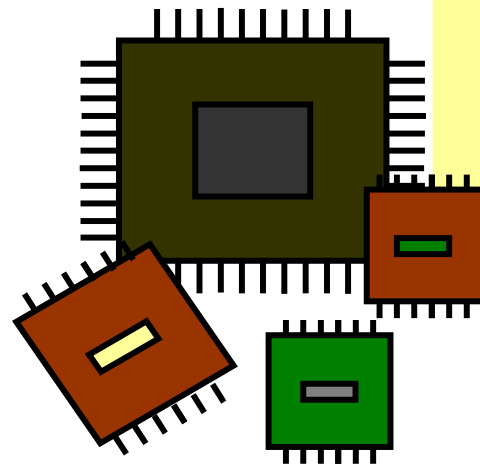
- Do not run the program – analyze it!
 - Using models based on the static properties of the software and the hardware
- Guaranteed reliable WCET bounds
 - Provided all models, input data and analysis methods are correct
- Trying to be as tight as possible



Again: Causes of Execution Time Variation

- Execution characteristics of the software
 - A program can often execute in many different ways
 - Input data dependencies
 - Application characteristics
- Timing characteristics of the hardware
 - Clock frequency
 - CPU characteristics
 - Memories used
 - ...

```
foo(x,i):  
  while(i < 100)  
    if (x > 5) then  
      x = x*2;  
    else  
      x = x+2;  
    end  
    if (x < 0) then  
      b[i] = a[i];  
    end  
    i = i+1;  
  end
```



WCET analysis phases

➤ Flow analysis

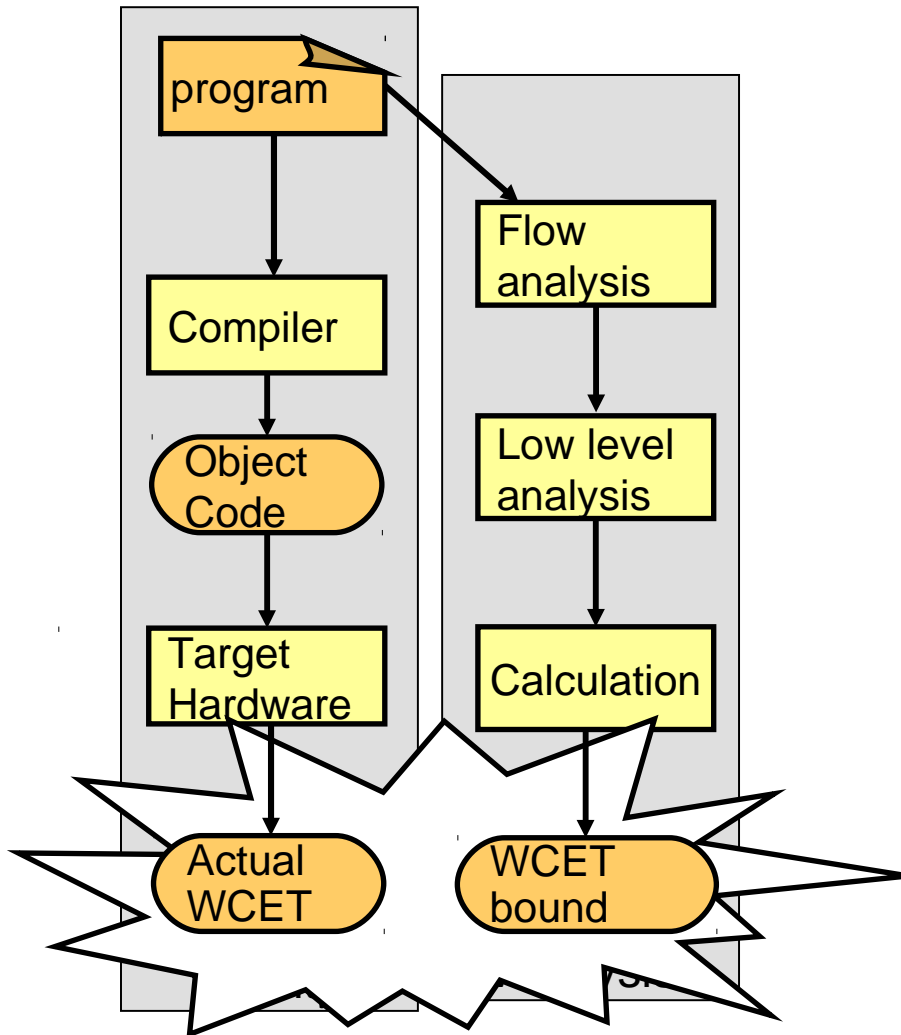
- Bound the number of times different program parts may be executed (SW analysis)

➤ Low-level analysis

- Bound the execution time of different program parts (HW analysis)

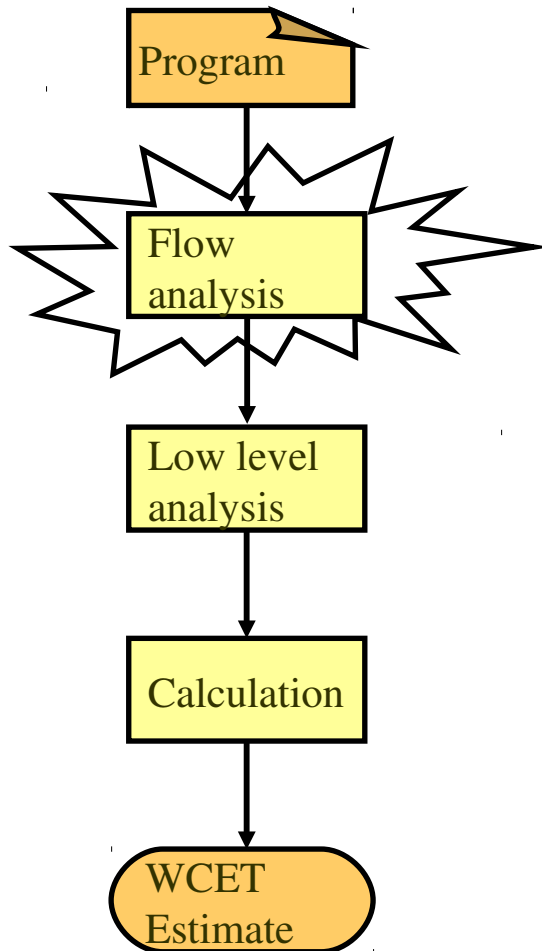
➤ Calculation

- Combine flow- and low-level analysis results to derive an upper WCET bound



Flow Analysis

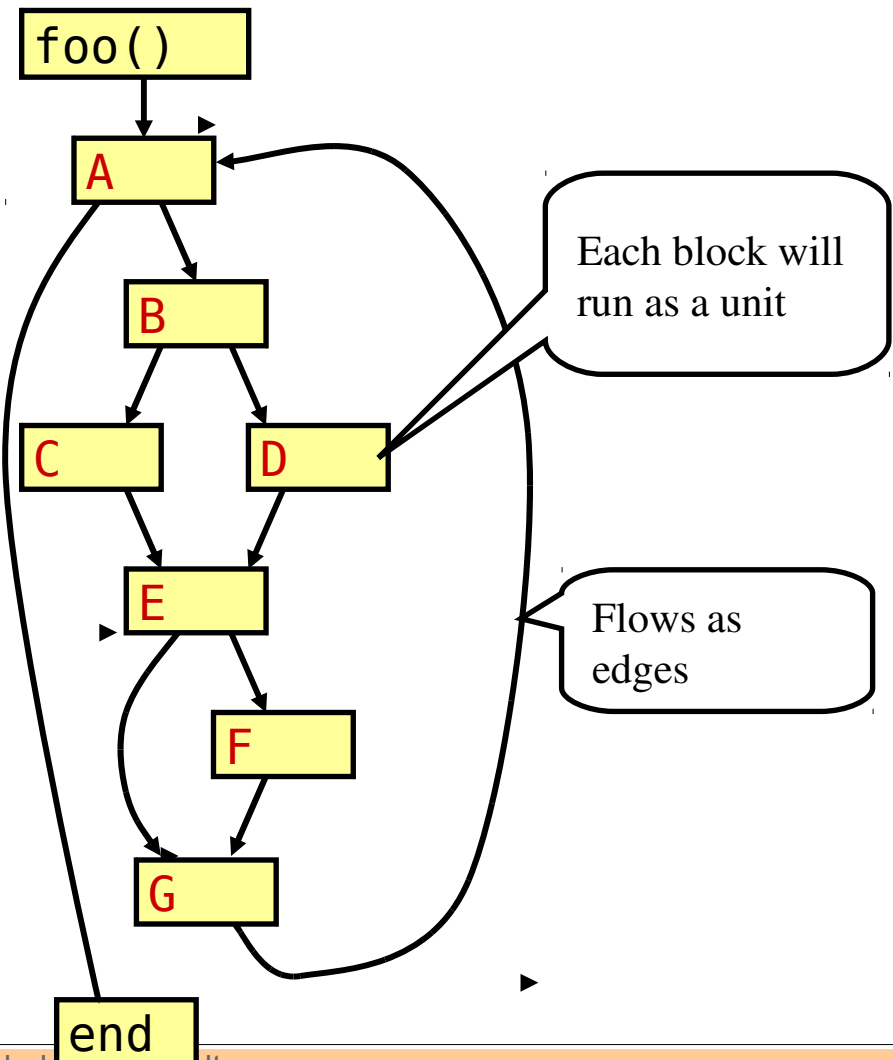
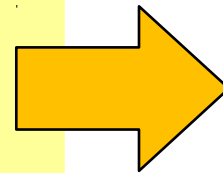
- Provides bounds on the number of times different program parts may be executed
 - Valid for all possible executions
- Examples of provided info:
 - Bounds of loop iterations
 - Bounds on recursion depth
 - Infeasible paths
- Info provided by:
 - Static program analysis
 - Manual annotations



The control-flow graph

```
foo(x,i):
```

```
A:   while(i < 100)
B:     if (x > 5) then
C:       x = x*2;
      else
D:       x = x+2;
      end
E:     if (x < 0) then
F:       b[i] = a[i];
      end
G:     i = i+1;
      end
end
```



Example: Loop bounds

```
foo(x,i):  
A:   while(i < 100)  
B:     if (x > 5) then  
C:       x = x*2;  
       else  
D:       x = x+2;  
       end  
E:     if (x < 0) then  
F:       b[i] = a[i];  
       end  
G:     i = i+1;  
end
```

• Loop bound:

- Depends on possible values of input variable i
 - E.g. if $1 \leq i \leq 10$ holds for input value i then loop bound is 100
- In general, a very difficult problem
- However, solvable for many types of loops

• Requirement for basic finiteness

- All loops must be upper bound

Example: Infeasible path

```
foo(x,i):  
A:   while(i < 100)  
B:     if (x > 5) then  
C:       x = x*2;  
       else  
D:       x = x+2;  
       end  
E:     if (x < 0) then  
F:       b[i] = a[i];  
       end  
G:     i=i+1;  
       end
```

- **Infeasible path:**

- Path A-B-C-E-F-G can not be executed
- Since C implies $\neg F$
- If $(x > 5)$ then it is not possible that $(x*2) < 0$

- **Limits statically allowed executions**

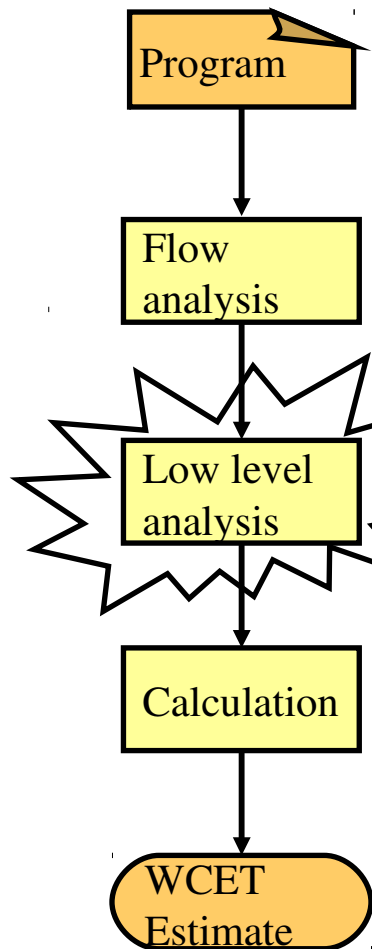
- Might tighten the WCET estimate

Example: Triangular Loop

```
triangle(a,b):  
A:   loop(i=1..100)  
B:   loop(j=i..100)  
C:       a[i,j]=...  
       end loop  
       end loop
```

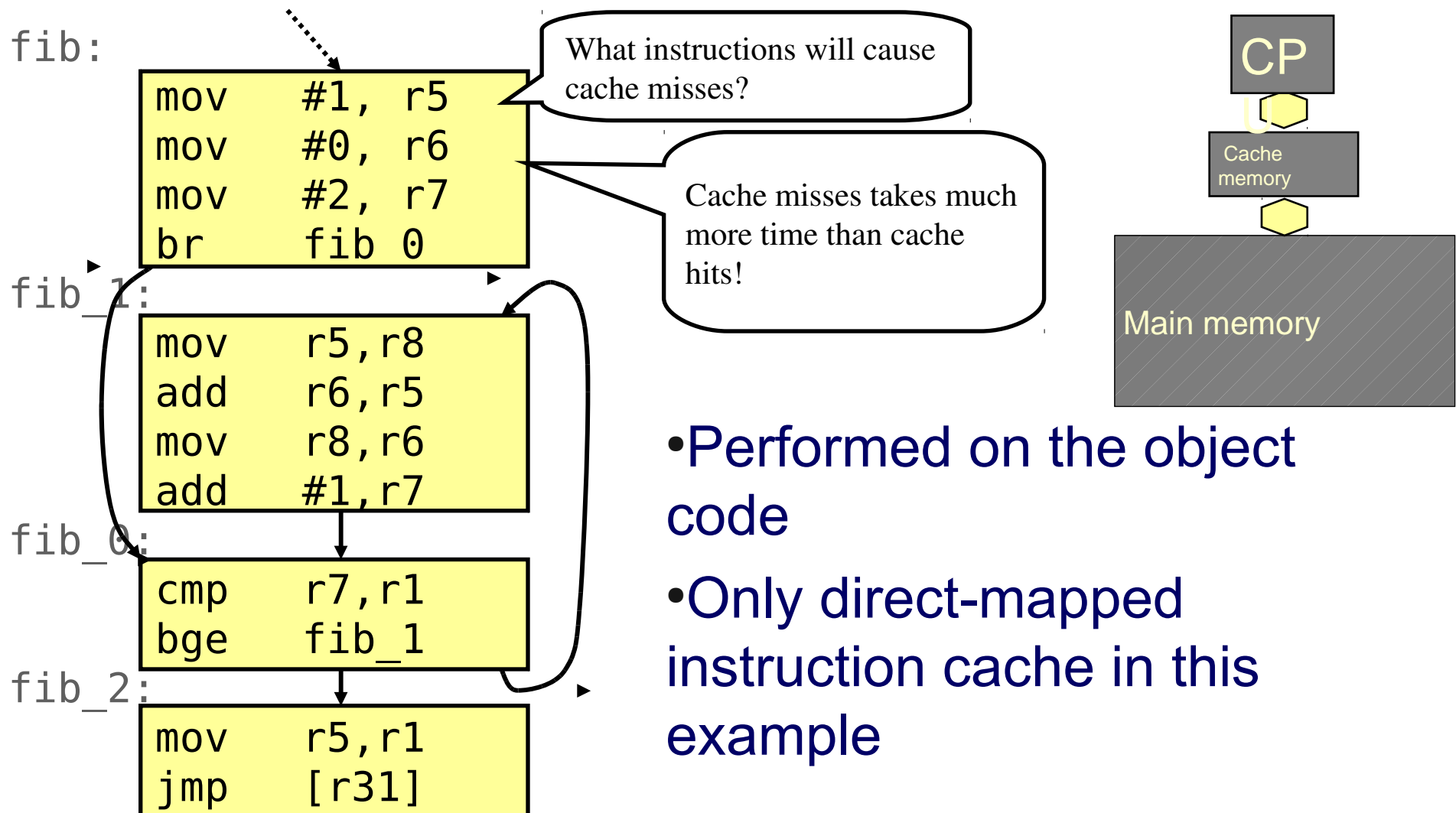
- **Two loops:**
 - Loop A bound: 100
 - Local B bound: 100
- **Block C:**
 - By loop bounds:
 $100 * 100 = 10\ 000$
 - **But actually:**
 $100 + \dots + 1 = 5\ 050$
- **Limits statically allowed executions**
 - Might tighten the WCET estimate

Low-Level Analysis

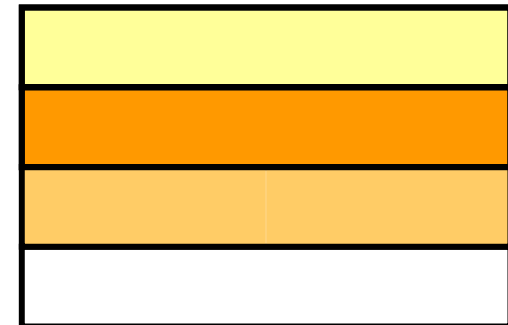
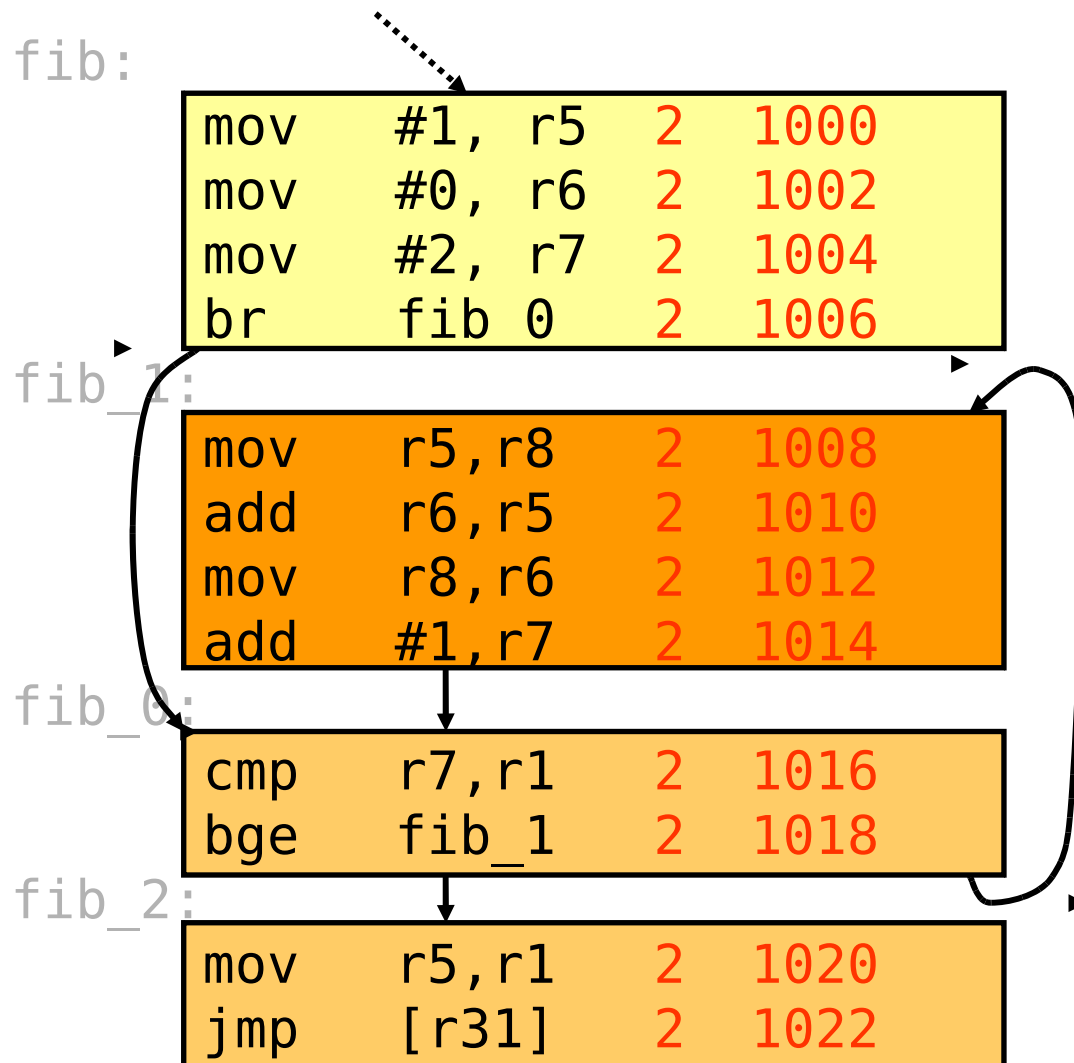


- Determine execution time bounds for program parts
 - Focus of most WCET-related research
- Using a model of the target HW
 - The model does not need to model all HW details
 - However, it should safely account for all possible HW timing effects
- Works on the binary, linked code
 - The executable program

Example: Cache analysis

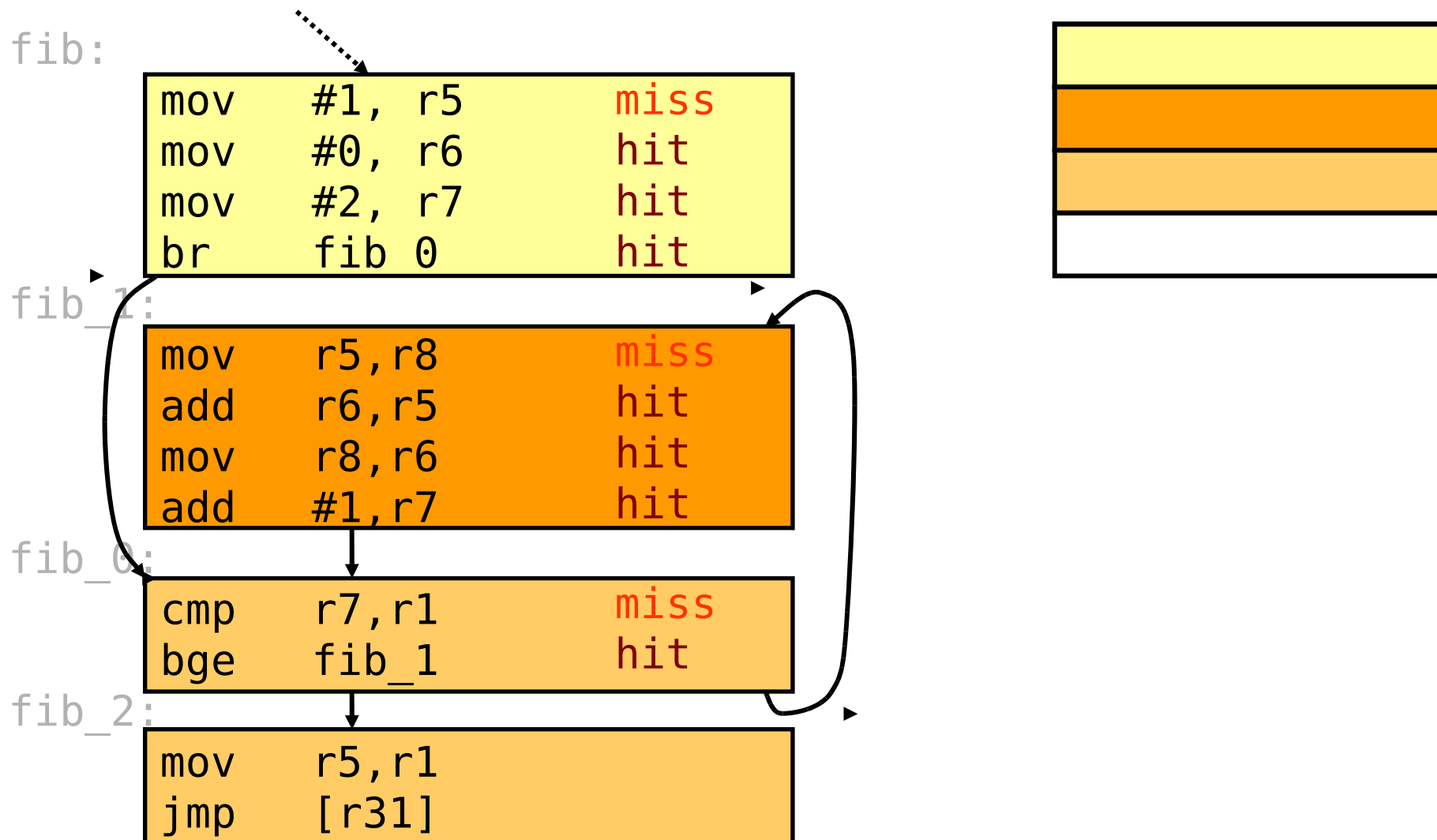


Example: Cache analysis

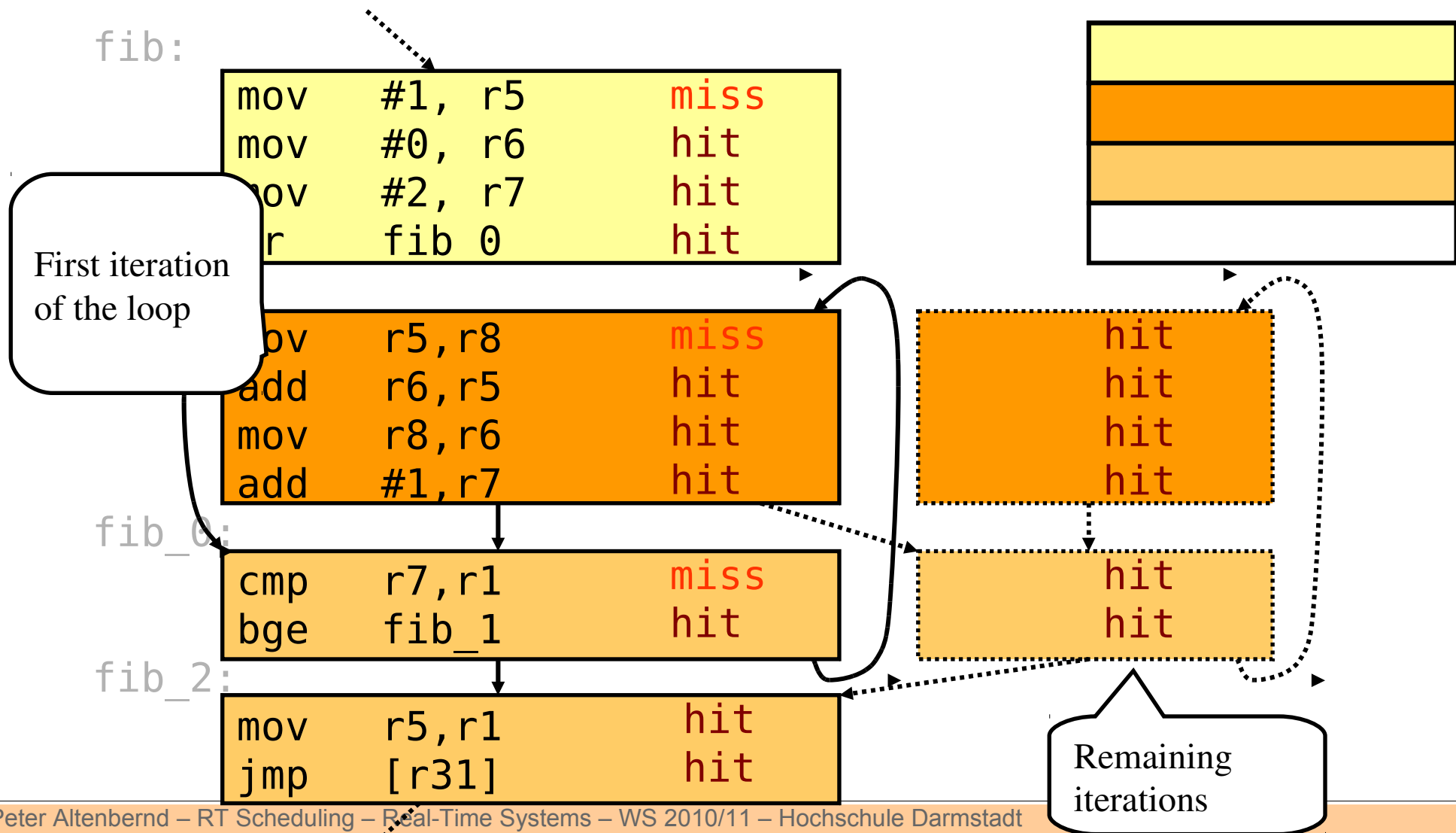


- Mapping to instruction cache

Example: Cache analysis

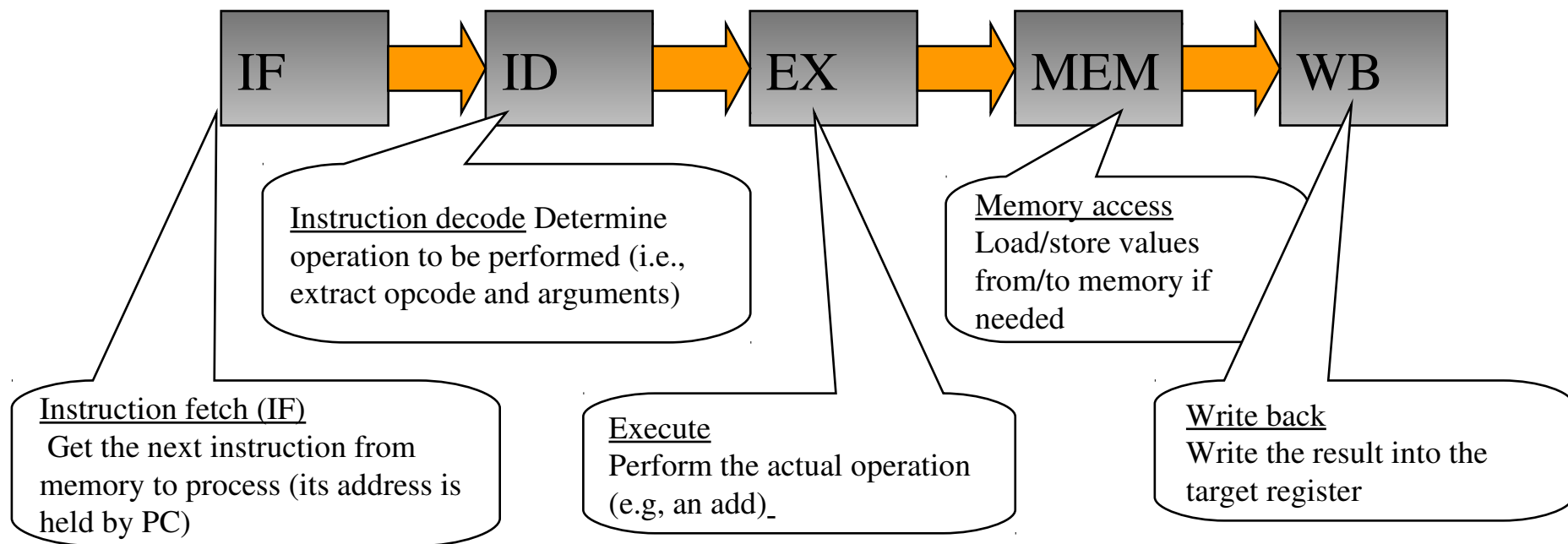


Example: Cache analysis



Example: CPU pipelines

- Observation: Most instructions go through same stages in the CPU
- Example: Classic RISC 5-stage pipeline



CPU pipelines

□ Idea: Overlap the CPU stages of the instructions to achieve speed-up

□ No pipelining:

- Next instruction cannot start before previous one has finished all its stages

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|-----|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| IF | Orange | Grey | Grey | Grey | Grey | Yellow | Grey | Grey | Grey | Grey |
| ID | Grey | Orange | Grey | Grey | Grey | Grey | Yellow | Grey | Grey | Grey |
| EX | Grey | Grey | Orange | Grey | Grey | Grey | Grey | Yellow | Grey | Grey |
| MEM | Grey | Grey | Grey | Orange | Grey | Grey | Grey | Grey | Yellow | Grey |
| WB | Grey | Grey | Grey | Grey | Orange | Grey | Grey | Grey | Grey | Yellow |

□ Pipelining:

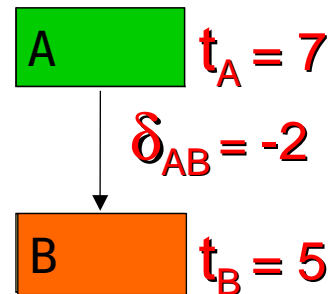
- In principle: Speed-up = length of pipeline
- However, often dependencies between instructions

| | 1 | 2 | 3 | 4 | 5 | 6 |
|-----|--------|--------|--------|--------|--------|--------|
| IF | Orange | Yellow | Grey | Grey | Grey | Grey |
| ID | Grey | Orange | Yellow | Grey | Grey | Grey |
| EX | Grey | Grey | Orange | Yellow | Grey | Grey |
| MEM | Grey | Grey | Grey | Orange | Yellow | Grey |
| WB | Grey | Grey | Grey | Grey | Orange | Yellow |

Example: Simple Pipeline

```
foo(x,i):
```

```
A:   while(i < 100)
B:     if (x > 5) then
C:       x = x*2;
        else
D:       x = x+2;
        end
E:     if (x < 0) then
F:       b[i] = a[i];
        end
G:     i = i+1;
      end
```



| | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|----|---|---|---|---|---|---|---|
| IF | | | | | | | |
| EX | | | | | | | |
| M | | | | | | | |
| F | | | | | | | |

| | 1 | 2 | 3 | 4 | 5 |
|----|---|---|---|---|---|
| IF | | | | | |
| EX | | | | | |
| M | | | | | |
| F | | | | | |

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|----|---|---|---|---|---|---|---|---|---|----|
| IF | | | | | | | | | | |
| EX | | | | | | | | | | |
| M | | | | | | | | | | |
| F | | | | | | | | | | |

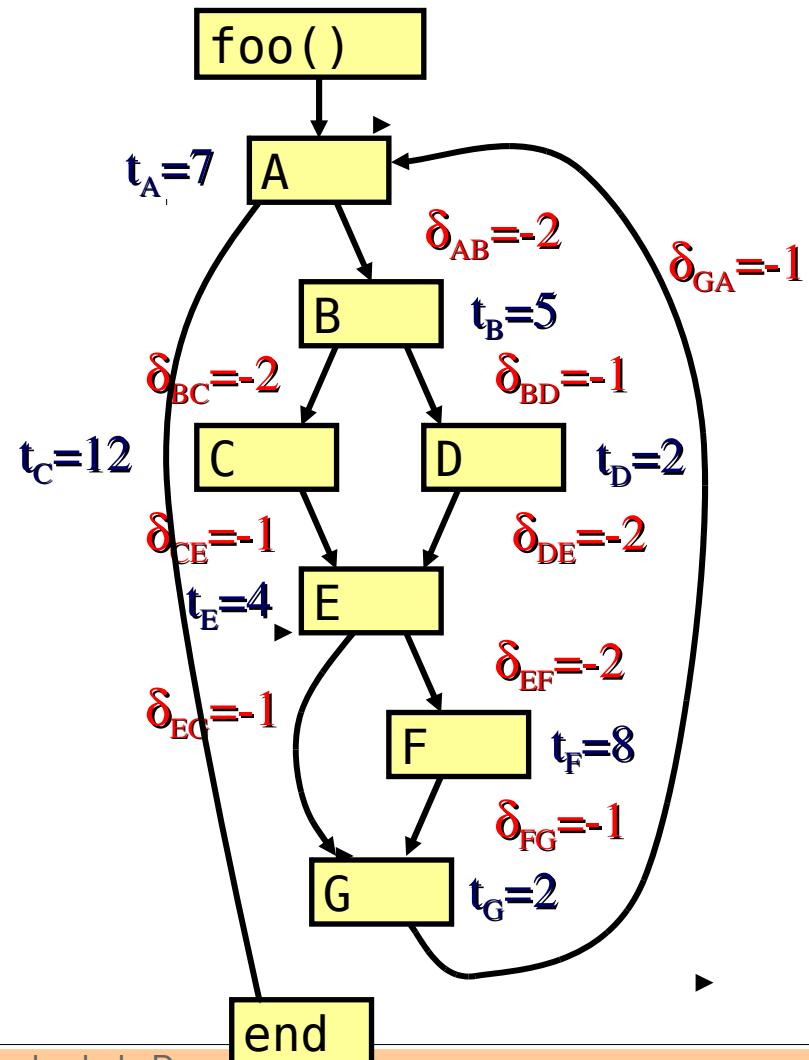
$t_{AB} = 10$

$$\delta_{AB} = 10 - (7 + 5) = -2$$

Example: Pipeline result

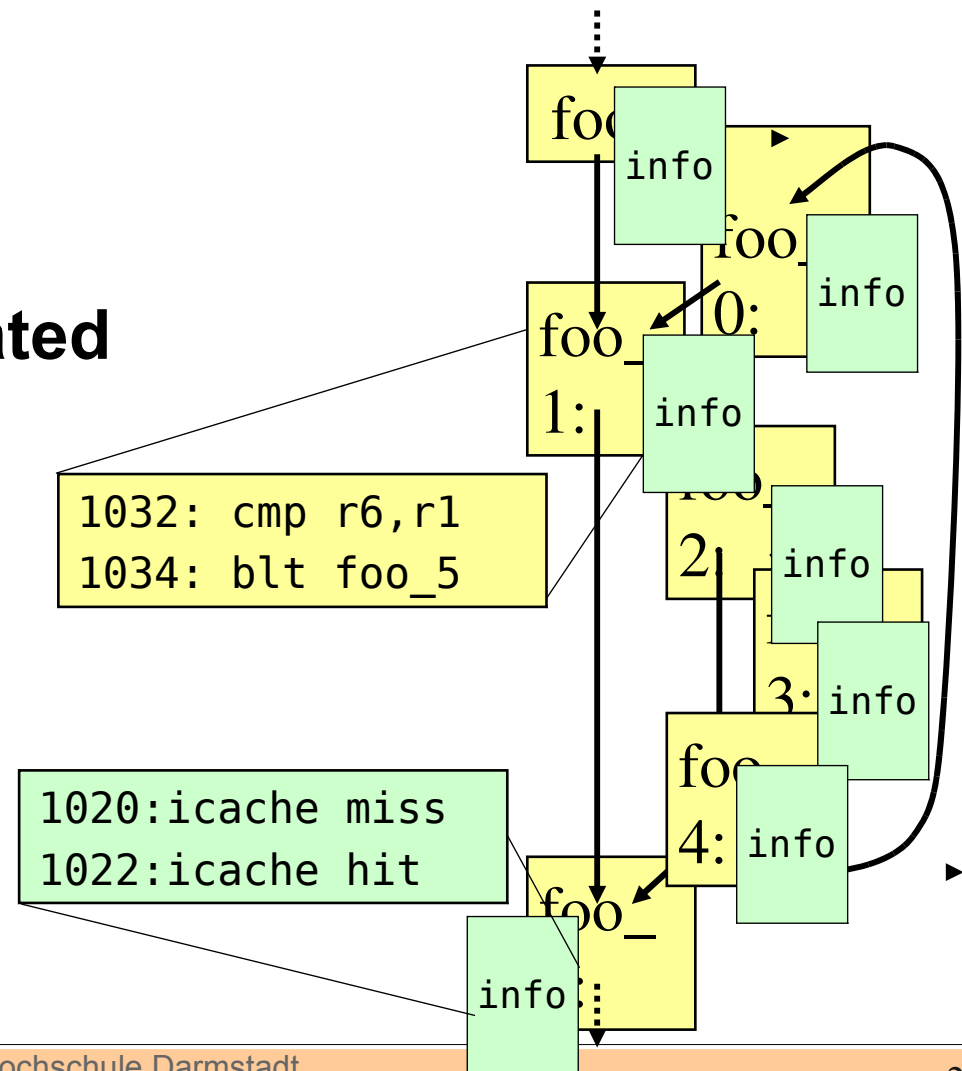
```
foo(x,i):
```

```
A:   while(i < 100)
B:     if (x > 5) then
C:       x = x*2;
      else
D:       x = x+2;
      end
E:     if (x < 0) then
F:       b[i] = a[i];
      end
G:     i = i+1;
      end
end
```

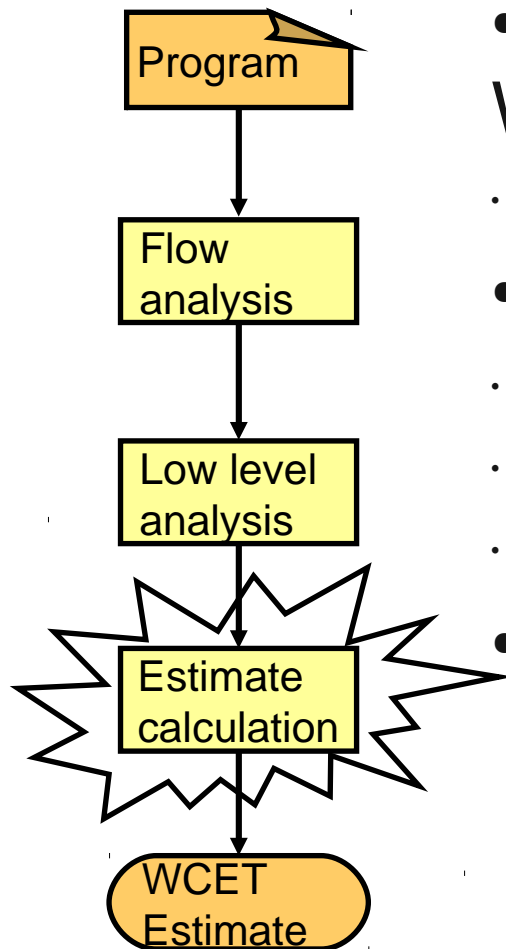


Cache & Pipeline analysis

- Pipeline analysis might take cache analysis results as input
 - Instructions gets annotated with cache hit/miss
 - These misses/hits affect pipeline timing
- Complex HW require integrated cache & pipeline analysis



Calculation



- Derive an upper bound on the program's WCET

- Given flow and timing information

- Several approaches used:

- Tree-based

- **Path-based**

- Constraint-based (IPET)

- Properties of approaches:

- Flow information handled

- Object code structure allowed

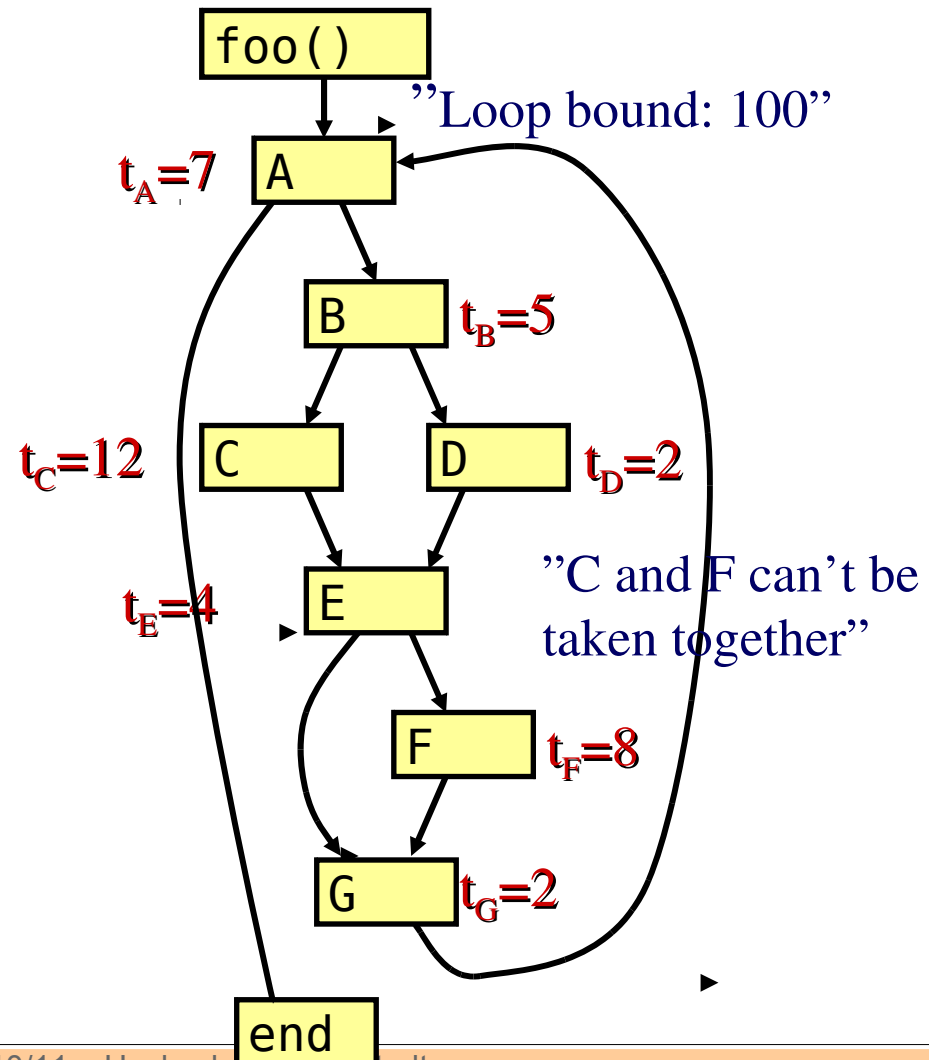
- Modeling of hardware timing

- Solution complexity

Example: Combined flow analysis and low-level analysis result

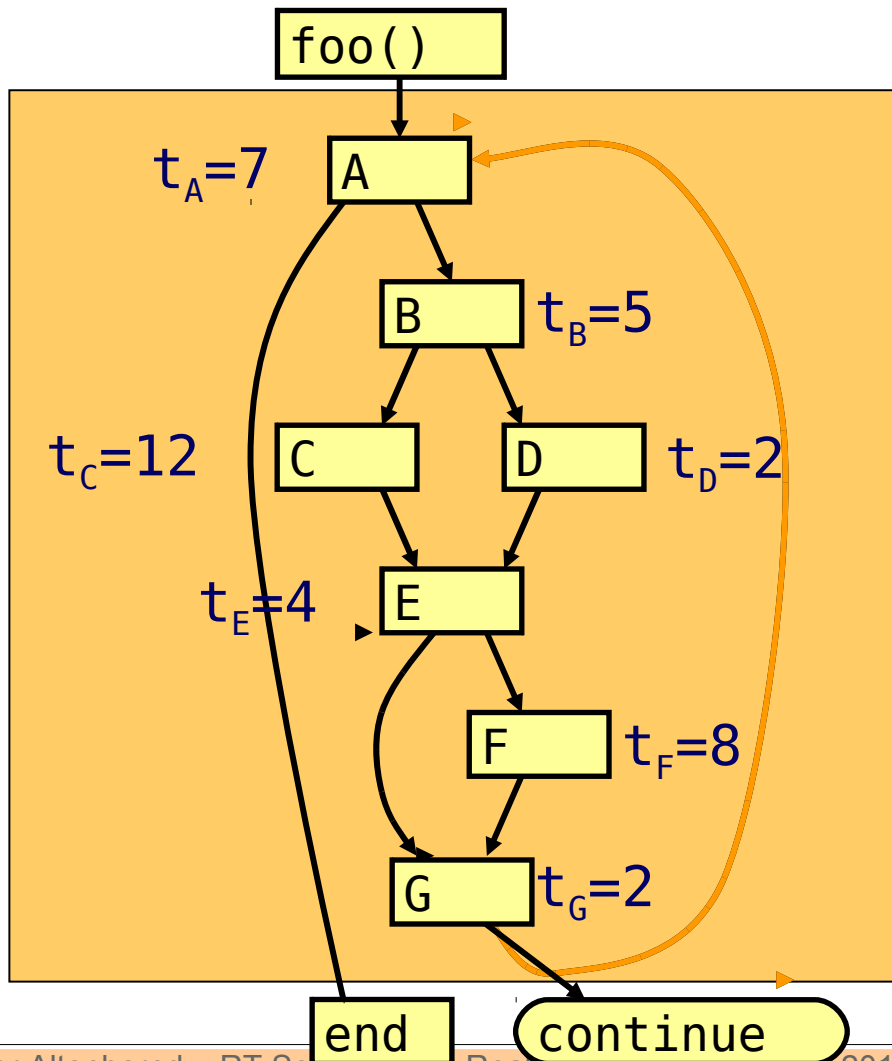
```
foo(x,i):
```

```
A:  while(i < 100)
B:    if (x > 5) then
C:      x = x*2;
      else
D:      x = x+2;
      end
E:    if (x < 0) then
F:      b[i] = a[i];
      end
G:    i = i+1;
      end
end
```



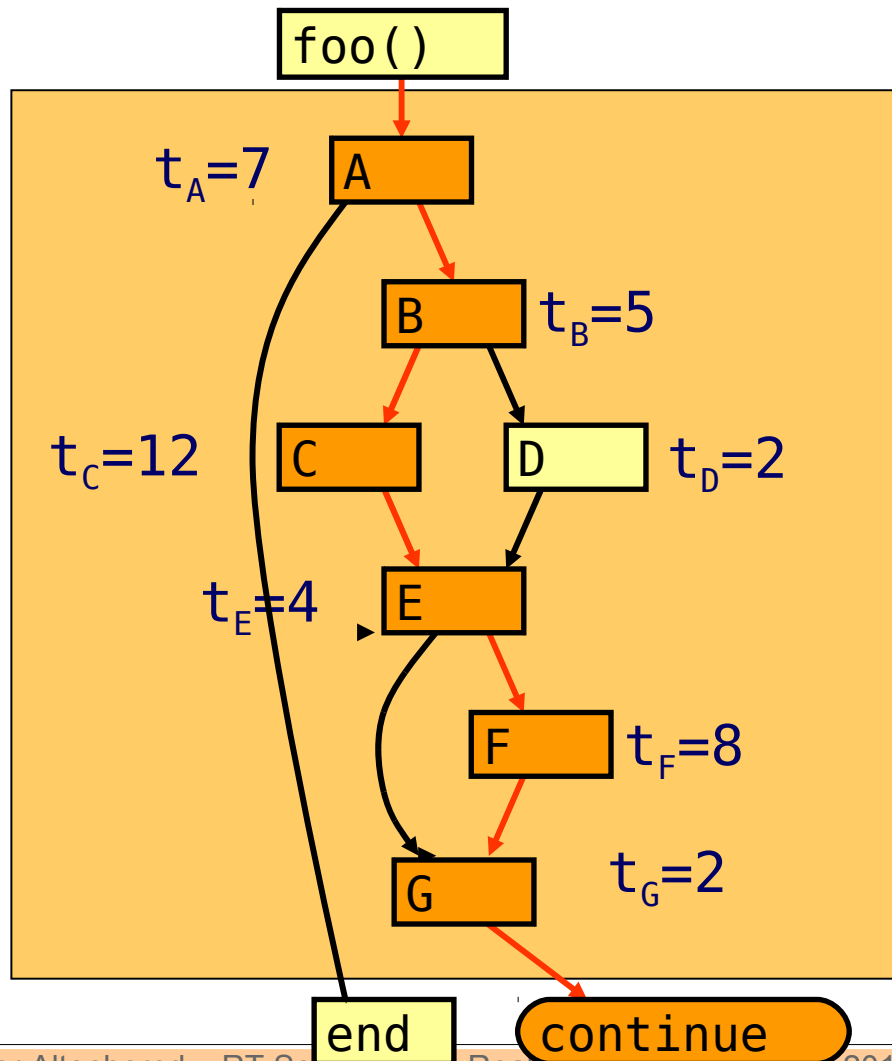
Path-Based Calc

```
foo(x,i):  
A:  while(i < 100)  
B:    if (x > 5) then  
C:      x = x*2;  
      else  
D:        x = x+2;  
      end  
E:    if (x < 0) then  
F:      b[i] = a[i];  
      end  
G:    i = i+1;  
      end
```



- Find longest path
- One loop at a time
- Prepare the loop
- Remove back edges
- Redirect to special continue nodes

Path-Based Calculation



- **Longest path:**

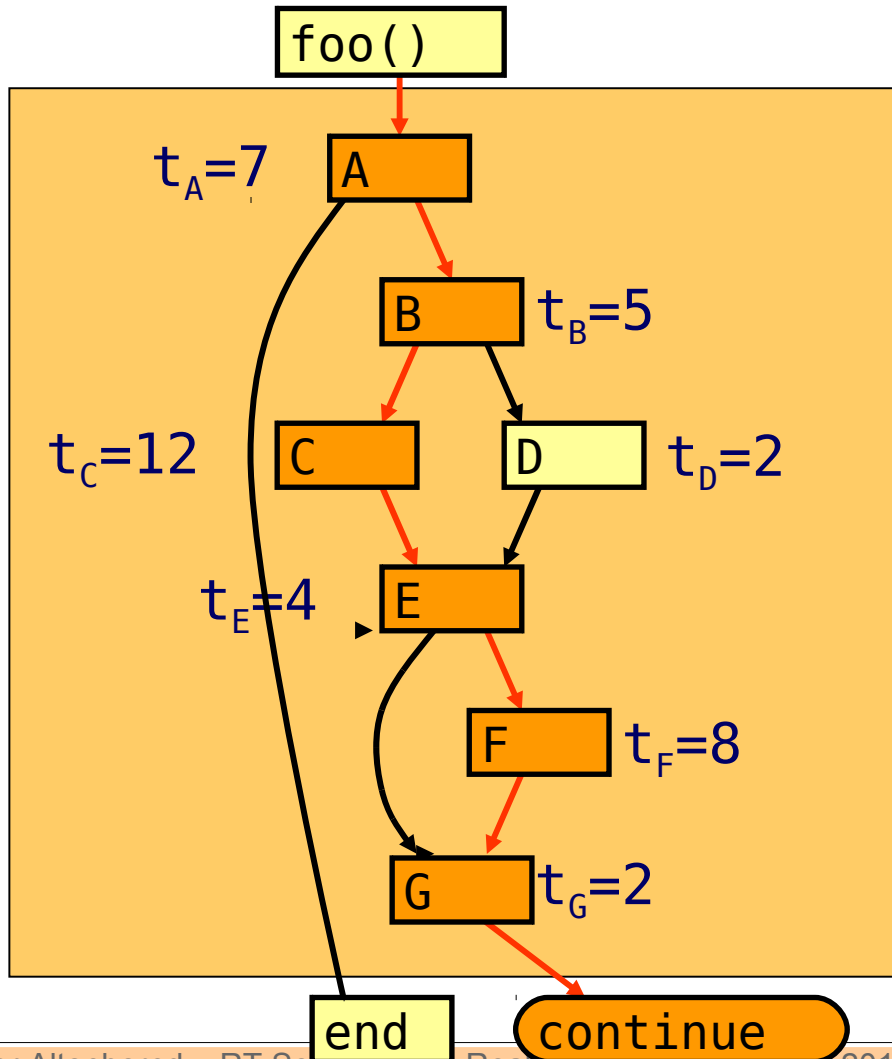
- A-B-C-E-F-G
- $7+5+12+4+8+2=$
38 cycles

- **Total time:**

- 100 iterations
- 38 cycles per iteration
- Total: 3800 cycles

Path-Based Calc

```
foo(x,i):  
A:  while(i < 100)  
B:    if (x > 5) then  
C:      x = x*2;  
      else  
D:        x = x+2;  
      end  
E:    if (x < 0) then  
F:      b[i] = a[i];  
      end  
G:    i = i+1;  
      end
```



C and F can never execute together

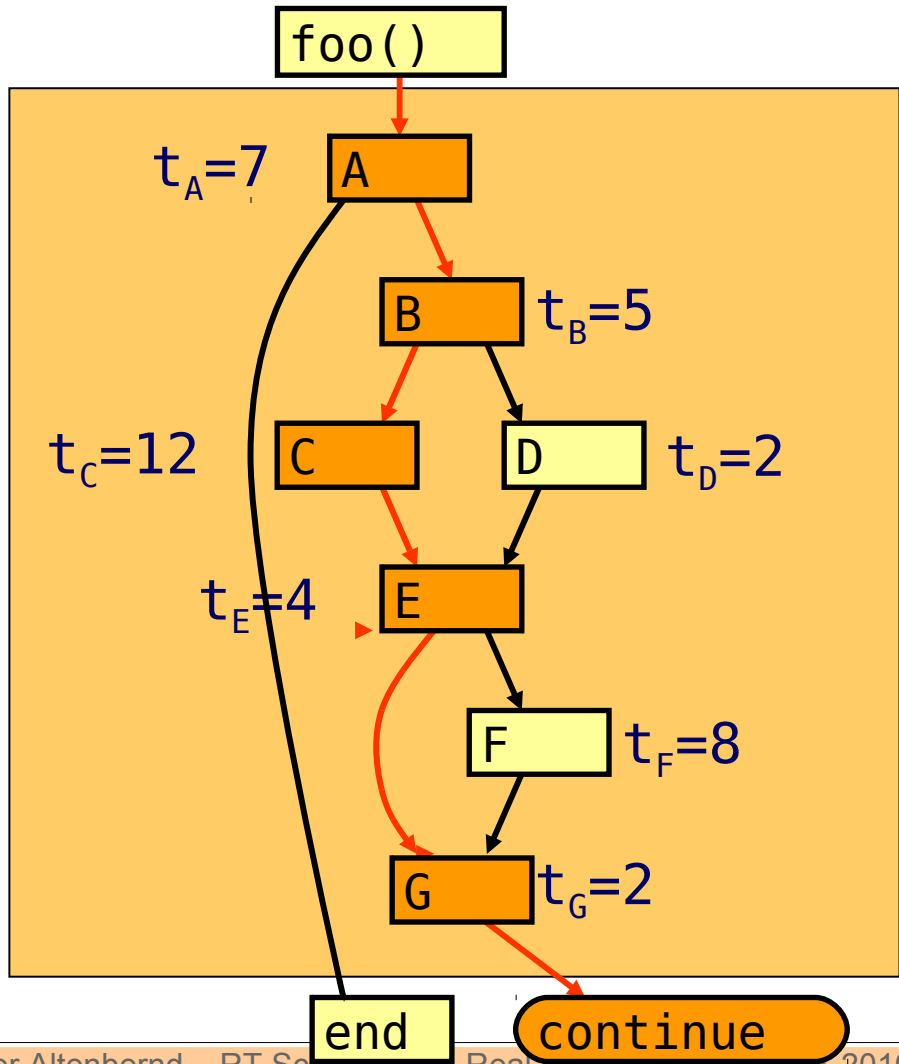
- Infeasible path:
 - A-B-C-E-F-G
 - Ignore, look for next

Path-Based Calc

```

foo(x,i):
A:  while(i < 100)
B:    if (x > 5) then
C:      x = x*2;
      else
D:      x = x+2;
      end
E:    if (x < 0) then
F:      b[i] = a[i];
      end
G:    i = i+1;
      end
end
    
```

C and F can never execute together



- **Infeasible path:**
 - A-B-C-E-F-G
 - Ignore, look for next
- **New longest path:**
 - A-B-C-E-G
 - 30 cycles
- **Total time:**
 - Total: 3000 cycles